

MSO, groups and graphs

Pytheas

Institut de mathématiques de Marseille

June 2021

Groups and graphs

- G finitely generated group
- G context-free = word problem of G is a context free language
- $\text{treewidth}(G) = \text{treewidth}(\text{undirected-Cayley}(G))$
- ...

MSO

- relational structure $S = \langle U; R_1, \dots, R_k \rangle$
- MSO formulas on S : $\phi(u, v) \equiv uR^*v$

$$\forall X, (u \in X \wedge (\forall x, y(x \in X \wedge xRy \implies y \in X))) \implies v \in X$$

MSO

- relational structure $S = \langle U; R_1, \dots, R_k \rangle$
- MSO formulas on S : $\phi(u, v) \equiv uR^*v$

$$\forall X, (u \in X \wedge (\forall x, y (x \in X \wedge xRy \implies y \in X))) \implies v \in X$$

- $H = (V, E)$ a graph (if labeled, $E = E_1 \cup \dots \cup E_k$)
- $MSO_1(H)$ when $U = V$ and $v_1Rv_2 \iff (v_1, v_2) \in E$
- $MSO_2(H)$ when $U = V \cup E$ and $vRe \iff e = (v, v')$

MSO

- relational structure $S = \langle U; R_1, \dots, R_k \rangle$
- MSO formulas on S : $\phi(u, v) \equiv uR^*v$

$$\forall X, (u \in X \wedge (\forall x, y (x \in X \wedge xRy \implies y \in X))) \implies v \in X$$

- $H = (V, E)$ a graph (if labeled, $E = E_1 \cup \dots \cup E_k$)
- $MSO_1(H)$ when $U = V$ and $v_1Rv_2 \iff (v_1, v_2) \in E$
- $MSO_2(H)$ when $U = V \cup E$ and $vRe \iff e = (v, v')$
- **Example:** K countably infinite clique

MSO

- relational structure $S = \langle U; R_1, \dots, R_k \rangle$
- MSO formulas on S : $\phi(u, v) \equiv uR^*v$

$$\forall X, (u \in X \wedge (\forall x, y(x \in X \wedge xRy \implies y \in X))) \implies v \in X$$

- $H = (V, E)$ a graph (if labeled, $E = E_1 \cup \dots \cup E_k$)
- $MSO_1(H)$ when $U = V$ and $v_1Rv_2 \iff (v_1, v_2) \in E$
- $MSO_2(H)$ when $U = V \cup E$ and $vRe \iff e = (v, v')$
- **Example:** K countably infinite clique

Theorem (Courcelle-1994)

If H is undirected and of bounded degree then $MSO_1(H)$ decidable **IFF** $MSO_2(H)$ decidable.

Decidability of MSO on f.g. groups

Corollary 4.1 (Kuske-Lohrey-2005)

If G is a finitely generated group, the following are equivalent:

- $MSO_1(\text{Cayley}(G))$ is decidable
- $\text{undirected-Cayley}(G)$ has finite treewidth
- G is context-free

Decidability of MSO on f.g. groups

Corollary 4.1 (Kuske-Lohrey-2005)

If G is a finitely generated group, the following are equivalent:

- $MSO_1(\text{Cayley}(G))$ is decidable
- undirected-Cayley(G) has finite treewidth
- G is context-free

- Muller-Schupp-1983*: context-free = virtually free

Decidability of MSO on f.g. groups

Theorem 3.10 (Kuske-Lohrey-2005)

Let G be a labeled connected graph of bounded degree such that $\text{Aut}(G)$ has only finitely many orbits on G , then the following are equivalent:

- 1 $\text{MSO}_1(G)$ decidable,
- 2 $\text{undirected}(G)$ has finite treewidth,
- 3 G is context free

Decidability of MSO on f.g. groups

Theorem 3.10 (Kuske-Lohrey-2005)

Let G be a labeled connected graph of bounded degree such that $\text{Aut}(G)$ has only finitely many orbits on G , then the following are equivalent:

- 1 $\text{MSO}_1(G)$ decidable,
- 2 $\text{undirected}(G)$ has finite treewidth,
- 3 G is context free

- (1) \implies (2) : **Seese-1991** + Courcelle-1994
- (3) \implies (1) : Muller-Schupp-1983 (see also Letichevskii-Smikun-1976?)

Theorem of Seese

- the hard one

Theorem (Seese-1991)

For any family of **planar** graphs for which MSO_1 is decidable, there is a uniform bound on the treewidth of graphs of the family.

Remember the clique... → **Seese's conjecture**

Theorem of Seese

- the hard one

Theorem (Seese-1991)

For any family of **planar** graphs for which MSO_1 is decidable, there is a uniform bound on the treewidth of graphs of the family.

Remember the clique... → **Seese's conjecture**

- the “easy” one

Theorem (Seese-1976, Phd thesis?)

For any family of graphs for which MSO_2 is decidable, there is a uniform bound on the treewidth of graphs of the family.

proof: *sprichst du Deutsch?*

MSO engineering

Minors in *MSO*₂

MSO engineering

Minors in MSO_2

- $R(x, y, D_V, D_E, C) \equiv$
after *deleting vertices* in D_V and *deleting edges* in D_E and
contracting edges in C , there is an edge from x to y

MSO engineering

Minors in MSO_2

- $R(x, y, D_V, D_E, C) \equiv$
after *deleting vertices* in D_V and *deleting edges* in D_E and
contracting edges in C , there is an edge from x to y

- “there is a minor such that ϕ ” \equiv
 $\exists D_V, D_E, C, \phi(R(\cdot, \cdot, D_V, D_E, C))$

MSO engineering

Minors in MSO_2

- $R(x, y, D_V, D_E, C) \equiv$
after *deleting vertices* in D_V and *deleting edges* in D_E and
contracting edges in C , there is an edge from x to y
- “there is a minor such that ϕ ” \equiv
 $\exists D_V, D_E, C, \phi(R(\cdot, \cdot, D_V, D_E, C))$
- Remark: we can express in MSO_1 that H is a minor of G
for a **fixed** $H \rightarrow$ planarity

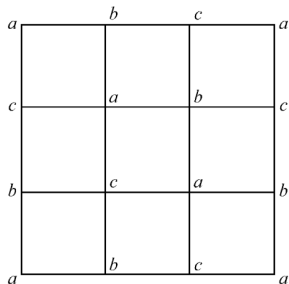
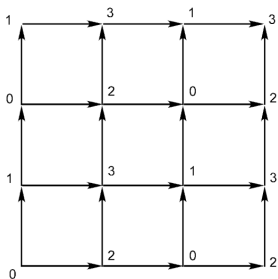
MSO engineering

n × *n*-grids

MSO engineering

$n \times n$ -grids

Proposition 5.14 page 340 of Courcelle-Engelfriet



In MSO_1

MSO engineering

Seese Theorem

MSO engineering

Seese Theorem

- with MSO, we can encode computation of a Turing machine on the grid starting from the SW-corner
- $M \mapsto \phi_M$
 $\phi_M \equiv$ *for any grid minor, the computation of M on this grid doesn't halt*

MSO engineering

Seese Theorem

- with MSO, we can encode computation of a Turing machine on the grid starting from the SW-corner
- $M \mapsto \phi_M$
 $\phi_M \equiv$ *for any grid minor, the computation of M on this grid doesn't halt*
- by the grid minor theorem, if G has infinite treewidth then G contains arbitrarily large grid minors and therefore

$$G \models \phi_M \iff M \text{ doesn't halt.}$$

- MSO_2 cannot be decidable on such G .